

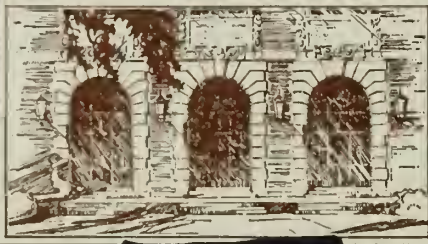
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A PARALLEL QR-ALGORITHM FOR TRIDIAGONAL SYMMETRIC MATRICES

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A Parallel QR-Algorithm for Tridiagonal Symmetric Matrices^{*}

by

Ahmed H. Sameh^{**} and David J. Kuck^{***}

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Abstract

We show that if the size of the tridiagonal matrix in any given iteration is n , then the parallel QR-algorithm requires $O(\log_2 n)$ steps with $O(n)$ processors per iteration and no square roots. This results in a speedup of $O(n/\log_2 n)$ and an efficiency of $O(1/\log_2 n)$.

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1. Introduction

Reinsch [1] proposed a stable QR algorithm for finding the eigenvalues of symmetric tridiagonal matrices that requires no square roots.

In this paper we present a version of his algorithm that is suitable for parallel computers. We give upper bounds on the time and number of processors required, per iteration.

Throughout this paper we assume that any number of processors may be used at any time, but we will give bounds on this number. Each processor can perform any of the four arithmetic operations in one time step, and there are no memory or data alignment time penalties. We also give the following definitions. If $p \geq 1$ processors are used, we denote the computation time by T_p . The speedup of a parallel algorithm which uses p processors over a serial algorithm is defined by $S_p = T_1/T_p \geq 1$, and the corresponding efficiency of the computation is given by $E_p = S_p/p \leq 1$.

We show that if the size of the tridiagonal matrix in any given iteration is n , then the parallel QR algorithm requires $O(\log_2 n)$ steps per iteration (and no square roots) using $O(n)$ processors. This results in a speedup of $O(n/\log_2 n)$ and an efficiency of $O(1/\log_2 n)$. This algorithm depends on a parallel scheme developed by Chen and Kuck [2], for solving linear triangular systems.

2. The Algorithm

One iteration of the QR algorithm can be expressed in the form [3],

$$\begin{aligned} Q(A-kI) &= R \\ \tilde{A} &= RQ^t \end{aligned} \quad (1)$$

where k is an origin shift, Q is orthogonal, R is upper triangular, and we assume that the tridiagonal matrix A is of order $n = 2^m$, for a positive integer m . Note that the tridiagonal matrix \tilde{A} is similar to $(A-kI)$ rather than A . Let the diagonal elements of $(A-kI)$ be denoted by a_i ($i = 1, 2, \dots, n$) and the off-diagonal elements by b_i ($i = 2, 3, \dots, n$). The orthogonal matrix Q is chosen as the product of $(n-1)$ plane rotations, i.e., $Q = p_{n-1}^n \dots p_2^3 p_1^2$, where p_j^{j+1} rotates rows j and $j+1$ annihilating the element in the position $(j+1, j)$,

$$p_j^{j+1} = \begin{bmatrix} 1 & & & & & \\ & \ddots & & & & \\ & & 1 & & & \\ & & & c_j & s_j & \\ & & & -s_j & c_j & \\ & & & & & \ddots & \\ & & & & & & 1 \end{bmatrix} \leftarrow \text{row } j$$

Therefore, if $p_{r-1}^r \dots p_2^3 p_1^2 (A-kI)$ is given by,

$$\begin{bmatrix} p_1 & q_2 & t_3 & & & \\ & p_2 & q_3 & t_4 & & \\ & & \text{---} & & & \\ & & & p_{r-1} & q_r & t_{r+1} \\ & & & & g_r & c_{r-1} b_{r+1} \\ & & & & b_{r+1} & a_{r+1} & b_{r+2} \\ & & & & & \text{---} & \end{bmatrix}$$

then it follows by induction that,

$$c_r = g_r/p_r$$

$$s_r = b_{r+1}/p_r \quad r = 1, 2, \dots, n-1 \quad (2)$$

$$q_{r+1} = c_{r-1} c_r b_{r+1} + s_r a_{r+1}$$

where,

$$g_r = c_{r-1} a_r - c_{r-2} s_{r-1} b_r \quad r = 1, 2, \dots, n \quad (3)$$

in which $c_0 = 1, s_0 = 0$. From (2) and (3) we obtain the recurrence relation,

$$c_r p_r = c_{r-1} a_r - c_{r-2} s_{r-1} b_r \quad r = 2, 3, \dots, n-1 \quad (4)$$

Let $w_r = c_r \prod_{i=1}^r p_i$, then (4) reduces to the second order linear recurrence

relation,

$$w_0 = 1, w_1 = \alpha_1$$

$$w_r = a_r w_{r-1} - b_r^2 w_{r-2} \quad r = 2, 3, \dots, n-1$$

Solving (5) is equivalent to solving the lower triangular system of equations,

$$Lw = e_1$$

where,

$$w^t = (w_0, w_1, \dots, w_{n-1}) ,$$

$$\text{and } l_{ij} = \begin{cases} 1 & i = j \\ -a_j & i = j + 1 \\ b_{j+1}^2 & i = j + 2 \\ 0 & \text{otherwise} \end{cases}$$

Using the identity $c_r^2 + s_r^2 = 1$, and defining $z_r^2 = \prod_{i=1}^r p_i^2$, $r = 1, 2, \dots,$

$n-1$, we obtain the first order linear recurrence relation

$$z_0^2 = w_0^2 = 1$$

$$z_r^2 = b_{r+1}^2 z_{r-1}^2 + w_r^2 \quad r = 1, 2, \dots, n-1$$

This is equivalent to the lower triangular system,

$$\tilde{L}\tilde{z} = \tilde{w}$$

where,

$$\tilde{w}^t = (w_0^2, w_1^2, \dots, w_{n-1}^2),$$

$$\tilde{z}^t = (z_0^2, z_1^2, \dots, z_{n-1}^2),$$

and

$$\tilde{x}_{ij} = \begin{cases} 1 & i = j \\ -b_i^2 & i = j + 1 \\ 0 & \text{otherwise} \end{cases}$$

Note that the squares of the subdiagonal elements rather than the elements themselves are the given data. So squaring these elements of the original matrix will cost only one step and $(n-1)$ processors, which is negligible compared to the time of finding all the eigenvalues of the tridiagonal matrix.

The linear systems (6) and (8) are solved sequentially. Chen and Kuck [2] have shown that any m -th order linear recurrence system of n equations, or any unit lower triangular system of bandwidth $m + 1$, can be solved in

$$T_p = (2 + \log_2 m) \log_2 n - \frac{1}{2} (\log_2^2 m + \log_2 m)$$

steps with $p = O(m^2 n)$ processors. Specifically, the system (6) can be solved in $(3 \log_2 n - 1)$ steps with no more than $4n$ processors. Once w is obtained, forming the right-hand side \tilde{w} in (8) requires one step with $(n-1)$ processors, and the system itself can be solved in $2 \log_2 n$ steps with $(n-1)$ processors. Thus, solving (6) and (8) requires $T_{p_1} = 5 \log_2 n$ steps

with $p_1 = 4n$ processors. From w and \tilde{z} we can obtain,

$$p_j^2 = z_j^2 / z_{j-1}^2 ,$$

$$c_j^2 = w_j^2 / z_j^2 , \quad j = 1, 2, \dots, n-1$$

$$s_j^2 = b_{j+1}^2 / p_j^2 ,$$

and,
$$p_n^2 = \eta^2 / z_{n-1}^2$$

in which $\eta = (a_n w_{n-1} - b_n^2 w_{n-2})$ and where we have used (3) and (9).

It can be shown [4] that the orthogonal matrix Q is lower Hessenberg in which $Q_{jj} = c_{j-1} c_j = w_{j-1} w_j / z_{j-1} z_j$ ($j = 1, 2, \dots, n-1$), $Q_{nn} = c_{n-1}$, and $Q_{j,j+1} = s_j$. Therefore, the elements of the tridiagonal matrix $\tilde{A} = RQ^t$ are given by,

$$\tilde{a}_j = \xi_j \tau_j + a_{j+1} s_j^2 ,$$

$$\tilde{b}_{j+1}^2 = p_{j+1}^2 s_j^2 , \quad j = 1, 2, \dots, n-1$$

and
$$\tilde{a}_n = \xi_n a_n - \xi_{n-1} b_n^2$$

where,

$$\tau_j = (b_{j+1}^2 + p_j^2) ,$$

$$\xi_j = w_{j-1} w_j / z_j^2 , \quad j = 1, 2, \dots, n-1$$

and
$$\xi_n = w_{n-1}^2 / z_{n-1}^2$$

We show in Figure 1 that the elements of \tilde{A} can be evaluated in $T_{p_2} = 4$

steps using $p_2 = 3n$ processors. Thus, the total time required is given by

$T_p = T_{p_1} + T_{p_2} = 4 + 5\log_2 n$ steps with $p = 4n$ processors. Reinsch [1] has

shown that on a serial computer the time required for one iteration is

$T_1 = 11n$ steps. Hence, our parallel algorithm yields a speedup

$S_p \approx 11n/5\log_2 n$ with an efficiency $E_p \approx 11/20\log_2 n$.

The linear systems (6) and (8) can be extremely ill-conditioned.

For example, for Wilkinson's matrix W_{21}^- [5], $a_i = 11 - i$ ($i = 1, 2, \dots, 21$)

and $b_i = 1$, the condition number of L , in (6), in the first iteration is of

the order 10^{-17} . We simulated the above algorithm on an IBM 360/75, and in

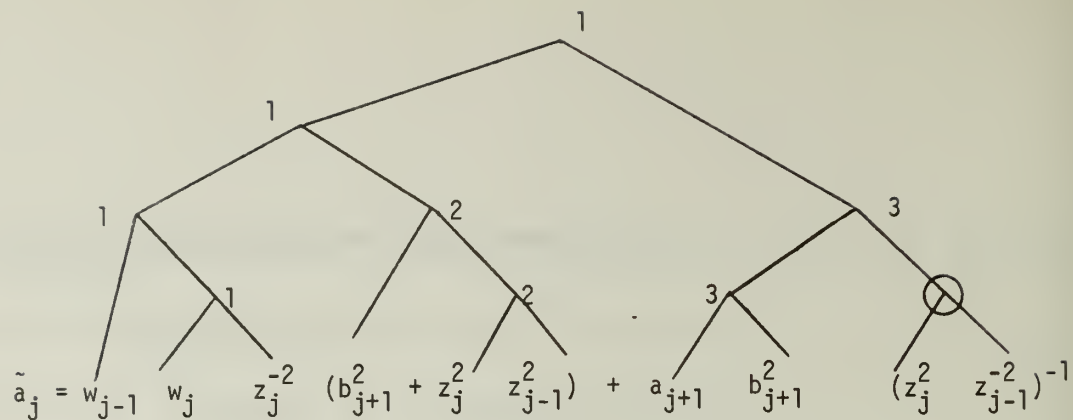
spite of such high condition number we obtained all the eigenvalues correct

to at least 9 decimal places. Wilkinson [6] has shown that the computed

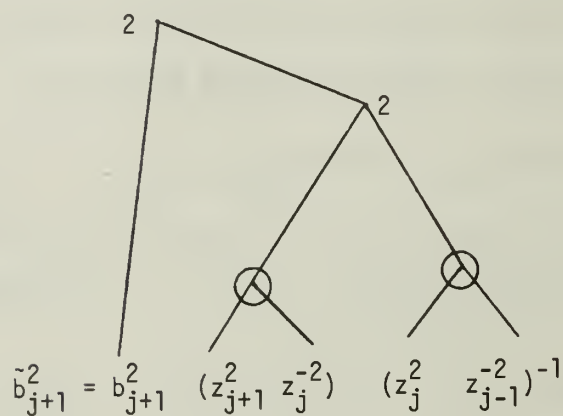
solution of a triangular system has low relative errors. Specifically,

system (8), $(\tilde{w}_i > 0, \tilde{x}_{ij} > 0, \tilde{x}_{ij} \leq 0 \text{ } i \neq j)$, will have low relative error

in the solution no matter how ill-conditioned \tilde{L} may be.



$j = 1, 2, \dots, n-1$



$j = 1, 2, \dots, n-2$

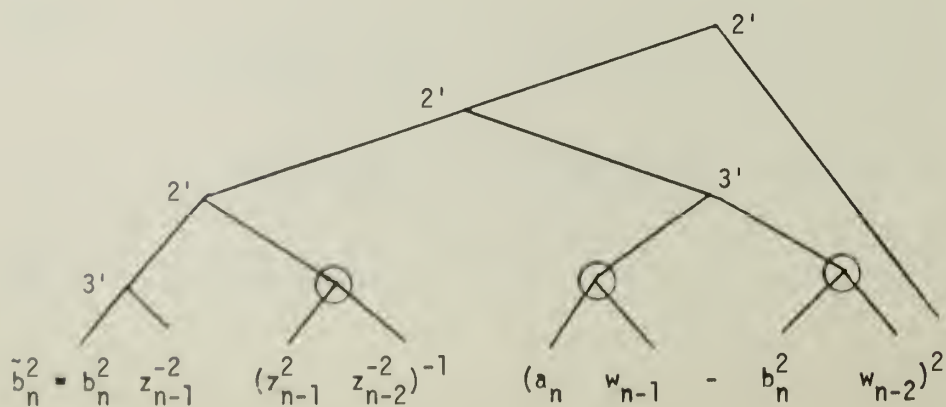
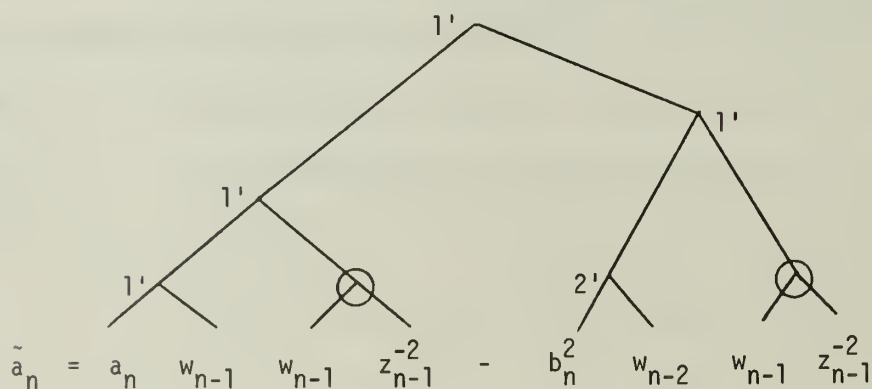


Figure 1

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